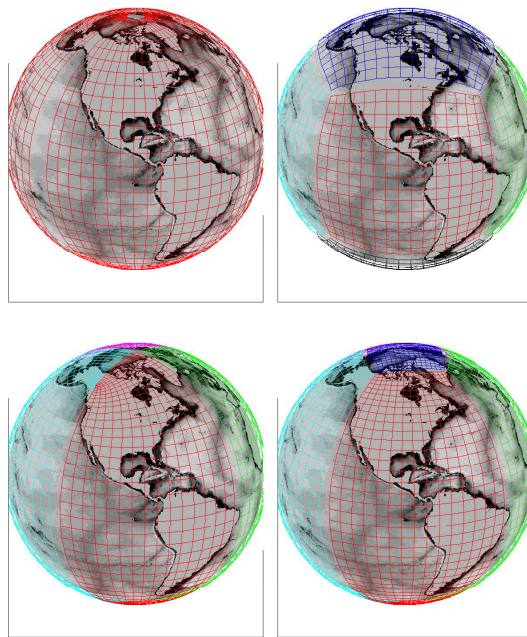


gcmfaces

a Matlab framework for the
analysis of gridded earth variables



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March 20, 2016

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Summary

gcmfaces is a Matlab framework designed to handle gridded earth variables; results of **MITgcm** ocean simulations originally ([Forget et al., 2015](#)). It allows users to seamlessly deal with various gridding approaches (e.g. see Fig.2) using compact and generic codes. It includes many basic and more evolved functionalities such as plotting, or computing transports, gradients, and budgets. **MITprof** is a complementary toolbox to handle in-situ ocean observations ([Forget et al., 2015](#)). This document provides guidelines to download and update the software (section 1) followed by the **gcmfaces** documentation. Its design and basic features are presented in sections 2 and 3. Higher level functions are illustrated in sections 4 and 5.

References

Forget, G., J.-M. Campin, P. Heimbach, C. N. Hill, R. M. Ponte, and C. Wunsch, 2015: ECCO version 4: an integrated framework for non-linear inverse modeling and global ocean state estimation. *Geoscientific Model Development*, **8** (10), 3071–3104, doi:10.5194/gmd-8-3071-2015, URL <http://www.geosci-model-dev.net/8/3071/2015/>.

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1 Download And Update

There are two ways to download and start using **gcmfaces** and **MITprof**:

1. download frozen copies: arguably the simplest method that will work in all computing environments (Linux, iOS, MS-windows).
2. use the **MITgcm** CVS server: this is the recommended method under Linux and iOS (assuming CVS was installed) since it has the major advantage that the codes can later easily be updated.

This section documents both methods and the setup of **gcmfaces**.

1.1 download frozen copies

The frozen copies of **gcmfaces** and **MITprof** are stored at

ftp://mit.ecco-group.org/ecco_for_las/version_4/checkpoints/

Download the latest versions¹, uncompress and untar them, and rename the two directories as ‘**gcmfaces**’ and ‘**MITprof**’. When starting Matlab, one will add these two directories to the path as explained in section 1.3.

1.2 use the MITgcm CVS server

Login to the **MITgcm** CVS server as explained in [this page](#)² then download the up to date versions of **gcmfaces** and **MITprof** by typing

```
cvs co -P -d gcmfaces MITgcm_contrib/gael/matlab_class
cvs co -P -d MITprof MITgcm_contrib/gael/profilesMatlabProcessing
```

All past and future evolutions of the codes can be traced using the **cvs** version control system. To update an existing copy of the codes and

¹c65u_gcmfaces.tar.gz and c65u_MITprof.tar.gz at the time of writing.

²http://mitgcm.org/public/using_cvs.html

22 take advantage of the latest developments one typically goes inside a di-
23 rectory and types 'cvs update -P -d' at the command line. If you are
24 new to **cvs** then you may want to read about the update command at
25 http://mitgcm.org/public/using_cvs.html.

26 **1.3 getting started with gcmfaces**

27 Download the LLC90 grid (Forget et al., 2015) directory at
28 ftp://mit.ecco-group.org/ecco_for_las/version_4/release1/nctiles_grid/
29 as shown in Fig. 1. Then start Matlab and load the grid by typing:

```
30 %add gcmfaces and MITprof directories to Matlab path:
31 p = genpath('gcmfaces/'); addpath(p);
32 p = genpath('MITprof/'); addpath(p);
33
34 %load nctiles_grid in memory:
35 grid_load;
36
37 %displays list of grid variables:
38 gcmfaces_global; disp(mygrid);
```

39 The applications in sections 4 and 5 further require downloading:
40 ftp://mit.ecco-group.org/ecco_for_las/version_4/release1/nctiles_climatology/
41 and adding the **m_map** plotting toolbox to the Matlab path:
42 <https://www.eoas.ubc.ca/~rich/map.html>

Figure 1: Directory structure that is consistent with the Matlab commands in Sect. 1.3. The `nctiles_climatology/` directory (14G) contains the monthly mean climatology of the ECCO v4, release 1 state estimate (Forget et al., 2015). `m_map` and `nctiles_climatology/` are not necessary in section 1.3 but are used to demonstrate higher-level functions in sections 4 and 5.

```
./
├── gcmfaces/ (Matlab toolbox)
├── MITprof/ (Matlab toolbox)
├── m_map/ (Matlab toolbox)
├── nctiles_grid/ (netcdf files)
├── release1/
│   ├── nctiles_climatology/ (netcdf files)
│   ├── mat/ (see section 5)
│   └── tex/ (see section 5)
```

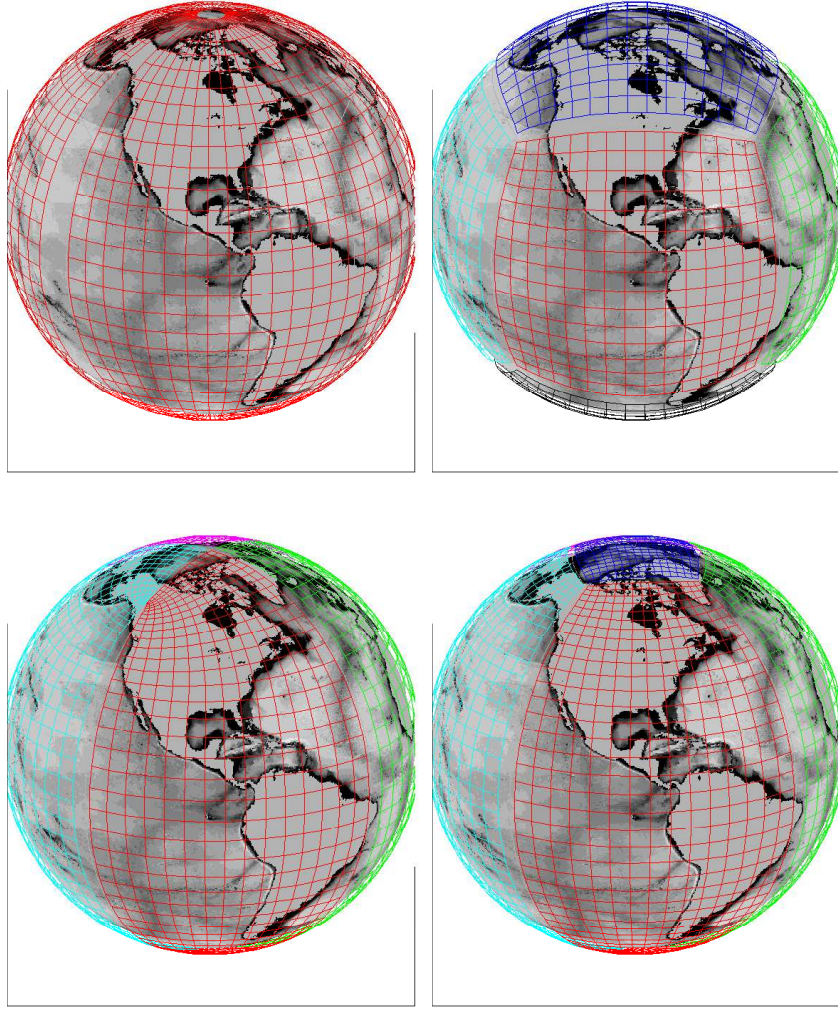


Figure 2: Four different ways of gridding the earth. Top left: lat-lon grid, mapping the earth to a single rectangular array ('face'). Top right: cube-sphere grid, mapping the earth to the six faces of a cube. Bottom right: lat-lon-cap 'LLC' grid (five faces). Bottom left: quadripolar grid (four faces). Faces are color-coded, and the ocean topography underlaid. Only a subset of the grid lines are shown in this depiction.

43 2 The gcmfaces class

44 The basic motivation for developing **gcmfaces** was to provide a unified frame-
 45 work that allows for the analysis of earth variables on various grids. Fig. 2
 46 shows four types of grids that are commonly used in ocean general circula-
 47 tion models (GCMs). Despite evident differences in GCM grid designs, such
 48 grids can all be represented as sets of connected arrays (or ‘faces’). This fact
 49 is illustrated in Fig. 3 for the LLC90 grid (bottom right panel in Fig.2) that
 50 is used in ECCO v4 (Forget et al., 2015).

51 The core of **gcmfaces** lies in its definition of a new Matlab data type
 52 (or ‘class’) that represents gridded earth variables as sets of connected ar-
 53 rays (the ‘@gcmfaces/’ subdirectory). An object of the gcmfaces class is
 54 stored in memory as shown in Table 1. The gcmfaces class inherits many
 55 of its basic operations (e.g., ‘+’) from the ‘double’ class as illustrated by
 56 **@gcmfaces/plus.m** (see Table 2). Objects of the gcmfaces class can thus be
 57 manipulated simply through compact and general expressions such as ‘a+b’
 58 (see section 3.3) that are robust to changes in grid design.

Table 1: Gridded variable represented using the gcmfaces class. In this case the LLC90 grid (Fig.2, bottom right) is used that has five faces (f1 to f5).

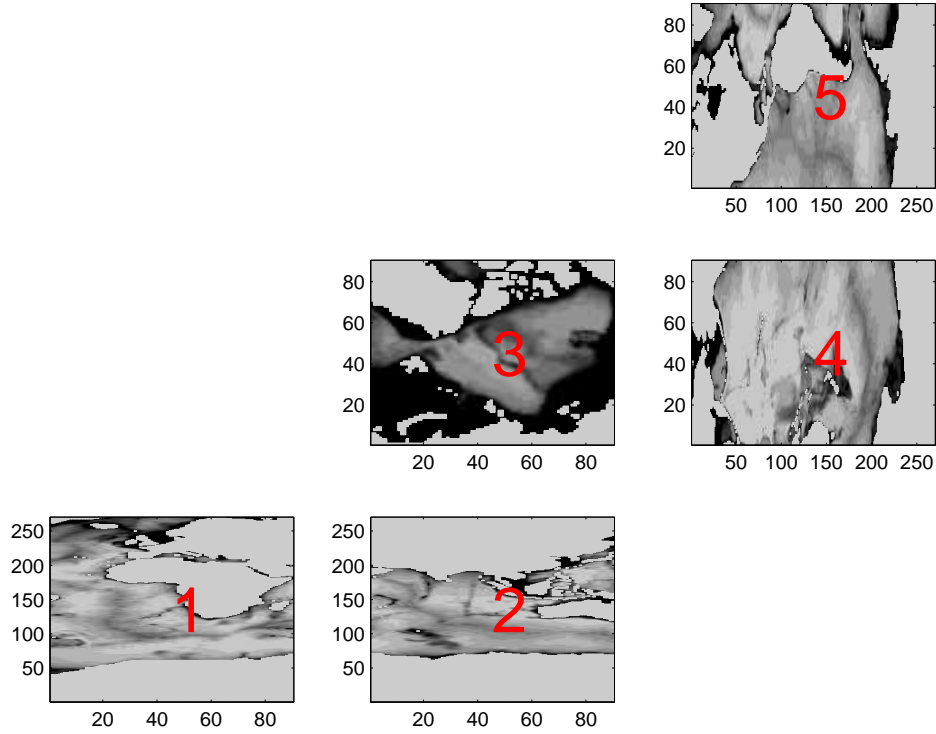
fld =	
nFaces:	5
f1:	[90x270 double]
f2:	[90x270 double]
f3:	[90x90 double]
f4:	[270x90 double]
f5:	[270x90 double]

Table 2: The '+' operation for gcmfaces objects (@gcmfaces/plus.m).

```
function r = plus(p,q)
%overloaded gcmfaces plus function :
% simply calls double plus function for each face data
% if any of the two arguments is a gcmfaces object

if isa(p,'gcmfaces'); r=p; else; r=q; end;
for iFace=1:r.nFaces;
    iF=num2str(iFace);
    if isa(p,'gcmfaces')&isa(q,'gcmfaces');
        eval(['r.f' iF '=p.f' iF '+q.f' iF ';'']);
    elseif isa(p,'gcmfaces')&isa(q,'double');
        eval(['r.f' iF '=p.f' iF '+q;']);
    elseif isa(p,'double')&isa(q,'gcmfaces');
        eval(['r.f' iF '=p+q.f' iF ';'']);
    else;
        error('gcmfaces plus: types are incompatible')
    end;
end;
```

Figure 3: Ocean topography displayed face by face for the LLC90 grid (Fig.2, bottom right). The face indices (from 1 to 5) are overlaid in red. Within each face, grid point indices increase from left to right and bottom to top in this view that reflects the data organization in memory (Tab. 1). This plot is generated by calling ‘example_display(1)’.



3 Basic Features

The representation of grid variables in memory is documented in section 3.1. Other key features of **gcmfaces** are the ‘exchange’ functions that connect faces (section 3.2) and the ‘overloading’ of common operations (section 3.3). I/O functions are discussed in section 3.4.

3.1 Grid Variables

In practice the **gcmfaces** framework gets activated by loading a grid in memory using the **grid_load.m** function. The default grid (LLC90) can be loaded in memory through a call to **grid_load.m** without any argument (as done in Sect. 1.3). For other grids, **grid_load.m** arguments need to be specified as explained by ‘help grid_load.m’. **grid_load.m** stores all grid variables in memory within a global structure named **mygrid** (Tab.3).

mygrid can be accessed in Matlab at any point by declaring it as ‘global mygrid;’ or using **gcmfaces_global.m**. The latter method additionally: (1) issues a warning when ‘mygrid has not yet been loaded to memory’; provides a few environment variables via **myenv**; adds gcmfaces directories to the path if needed. It should be stressed that gcmfaces functions often rely on **mygrid** and **myenv**. If they get deleted from memory (e.g., by a ‘clear all’) then a call to **grid_load.m** will re-activate gcmfaces properly.

The C-grid variables listed in Tab.3 follow the MITgcm naming convention (see sections 2.11 and 6.2.4 in [the MITgcm documentation](http://mitgcm.org/public/r2_manual/latest/online_documents/manual.pdf)³). In brief, XC, YC and RC denote longitude, latitude and vertical position of tracer variables. DXC, DYC, DRC and RAC are the corresponding grid spacings (in m) and grid cell areas (in m²). Another set of such fields (XG, YG, RF, DXG, DYG, DRF, RAZ) is necessary to complete the C-grid specification where velocity variables are shifted compared with tracer variables.

³http://mitgcm.org/public/r2_manual/latest/online_documents/manual.pdf

Table 3: List of grid variables contained in the mygrid global structure. The naming convention are directly inherited from the MITgcm. For details, see: http://mitgcm.org/public/r2_manual/latest/online_documents/manual.pdf

XC : [1x1 gcmfaces]	longitude (tracer)
YC : [1x1 gcmfaces]	latitude (tracer)
RC : [50x1 double]	depth (tracer)
XG : [1x1 gcmfaces]	longitude (vorticity)
YG : [1x1 gcmfaces]	latitude (vorticity)
RF : [51x1 double]	depth (velocity along 3rd dim)
DXC : [1x1 gcmfaces]	grid spacing (tracer, 1st dim)
DYC : [1x1 gcmfaces]	grid spacing (tracer, 2nd dim)
DRC : [50x1 double]	grid spacing (tracer, 3rd dim)
RAC : [1x1 gcmfaces]	grid cell area (tracer)
DXG : [1x1 gcmfaces]	grid spacing (vorticity, 1st dim)
DYG : [1x1 gcmfaces]	grid spacing (vorticity, 2nd dim)
DRF : [50x1 double]	grid spacing (velocity, 3rd dim)
RAZ : [1x1 gcmfaces]	grid cell area (vorticity)
AngleCS : [1x1 gcmfaces]	grid orientation (tracer, cosine)
AngleSN : [1x1 gcmfaces]	grid orientation (tracer, cosine)
Depth : [1x1 gcmfaces]	ocean bottom depth (tracer)
hFacC : [1x1 gcmfaces]	partial cell factor (tracer)
hFacS : [1x1 gcmfaces]	partial cell factor (velocity, 2nd dim)
hFacW : [1x1 gcmfaces]	partial cell factor (velocity, 1st dim)

85 The indexing and vector conventions also derive from the **MITgcm**. The
 86 indexing convention is illustrated for the LLC90 grid in Fig. 3. For a vector
 87 field the first component (U) points straight to the right of the page in Fig. 3,
 88 whereas the second component (V) points strait to the top of the page. The
 89 location of U components are shifted by half a grid point towards the left of
 90 the page, while the location of V components are shifted by half a grid point
 91 towards the bottom of the page (reflecting the C-grid approach).

92 3.2 Exchange Functions

93 Many quantities of interests (e.g., budgets) involve values from neighboring
 94 grid points that often need to be ‘exchanged’ between faces. This is achieved
 95 in practice by appending rows and columns at the sides of each face that
 96 are obtained from the neighboring faces – appending rows and columns from
 97 faces #2, 3, and 5 at the sides of face #1 in the case of Fig. 3 for exam-
 98 ple. These exchanges are operated by `exch_T_N.m` for tracer fields and
 99 by `exch_UV_N.m` for velocity fields. These functions are needed for ex-
 100 ample to compute temperature gradients (with `calc_T_grad.m`) and flow
 101 convergences (with `calc_UV_conv.m`) as illustrated in section 4.

102 3.3 Overloaded Functions

103 Table 2 depicts the ‘overloading’ of the ‘+’ operation by `@gcmfaces/plus.m`.
 104 In executing commands such as ‘fld+1’, Matlab will use `@gcmfaces/plus.m`
 105 if one of the arguments of ‘+’ (i.e. sum) is of the gcmfaces class. Many com-
 106 mon operations and functions are similarly overloaded in the ‘@gcmfaces/’
 107 directory that defines the gcmfaces class and its operations:

- 108 1. Logical operators: and, eq, ge, gt, isnan, le, lt, ne, not, or
- 109 2. Numerical operators: abs, angle, cat, cos, cumsum, diff, exp, imag,

110 log2, max, mean, median, min, minus, mrdivide, mtimes, nanmax,
 111 nanmean, nanmedian, nanmin, nanstd, nansum, plus, power, rdivide,
 112 real, sin, sqrt, std, sum, tan, times, uminus, uplus.

113 3. Indexing operators: subsasgn, subsref, find, get, set, squeeze, repmat.

114 It is worth mentioning the case of `@gcmfaces/subsasgn.m` (subscripted
 115 assignment) and `@gcmfaces/subsref.m` (subscripted reference) since they
 116 are some of the most commonly used Matlab functions. For example, if
 117 `fld` is of the ‘double’ class then ‘`tmp2=fld(1);`’ and ‘`fld(1)=1;`’ respectively
 118 call `subsref.m` and `subsasgn.m`. If `fld` is of the `gcmfaces` class instead then
 119 `@gcmfaces/subsref.m` behaves as follows:

120 `fld{n}` returns the n^{th} face data (i.e. an array).
 121 `fld(:, :, n)` returns the n^{th} vertical level (i.e. a `gcmfaces`).

122 And `@gcmfaces/subsasgn.m` behaves similarly but for assignments. The
 123 variables in Table 1 can also be accessed ‘manually’. For example:

124 `fld.nFaces` returns the `nFaces` attribute (double).
 125 `fld.f1` returns the face #1 array (double).

126 3.4 I/O Functions

127 Objects of the `gcmfaces` class can simply be saved to or read from file in Mat-
 128 lab’s own I/O format (.mat files). An alternative is to use `convert2array.m`
 129 or `convert2gcmfaces.m` to re-organize the faces data into one array (or vice
 130 versa) that can readily be written to or read from mat or binary files. The
 131 other file formats that are currently supported in the `gcmfaces` framework
 132 are: (1) the MITgcm ‘mds’ binary formats [documented here](#); (2) the nctiles
 133 format used to distribute ECCO v4 fields ([Forget et al., 2015](#)). When reading
 134 such files, the provided I/O functions (`rdmds2gcmfaces.m` and `read_nctiles.m`,
 135 respectively) reformat the input into `gcmfaces` objects on the fly.

136 4 Tutorial

137 Here it is assumed that the user has completed the installation procedure in
138 section 1.3 (including the installation of ‘nctiles_climatology/’ and ‘m_map/’).
139 `gcmfaces_demo.m` can then be executed by starting Matlab and typing

```
140 addpath('gcmfaces/');%the directory where gcmfaces_demo.m is found  
141 gcmfaces_demo;
```

142 that illustrates a few of the `gcmfaces` capabilities. As prompted by `gcmfaces_demo.m`
143 the user specifies a desired amount of explanatory text output. `gcmfaces_demo.m`
144 then proceeds through the examples while displaying explanations in the
145 Matlab command window. Before each example the user is prompted to
146 type the return key to proceed. The Matlab GUI and debugger can also be
147 used to run the examples line by line.

148 The first section of `gcmfaces_demo.m` illustrates IO (`grid_load.m`
149) and plotting capabilities (`example_display.m`). `gcmfaces` relies on
150 `m_map` (<https://www.eoas.ubc.ca/rich/map.html>) for geographical projec-
151 tions through the `m_map_gcmfaces` front-end that typically produces Fig.4.
152 The `convert2pcol` function provides an alternative to display results di-
153 rectly via ‘pcolor’ (Fig. 5). The second section of `gcmfaces_demo.m` focuses
154 on data processing capabilities such as interpolation (`example_interp.m`)
155 and smoothing (`example_smooth.m`). `example_interp.m` illustrates the
156 interpolation of `gcmfaces` fields to a lat-lon grid, and vice versa. `example_smooth.m`
157 integrates a diffusion equation, which illustrates computations of tracer gra-
158 dients and flux convergences. The third section of `gcmfaces_demo.m` illus-
159 trates computations of oceanic transports and stream-functions
160 (`example_transports.m`) and budgets (`example_budgets.m`).

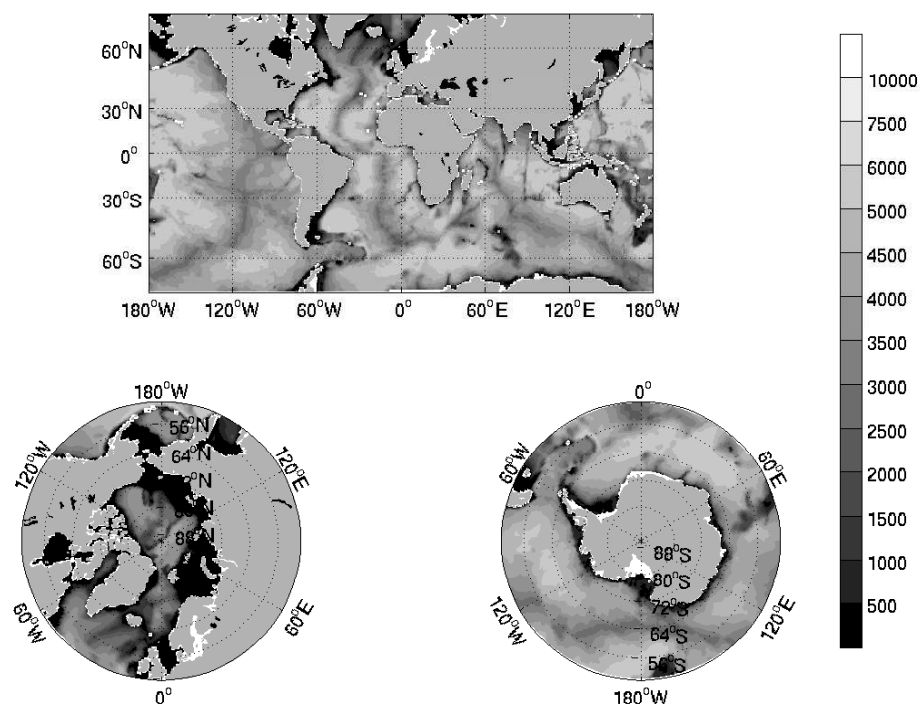


Figure 4: Same as Fig.3 but plotted in geographical coordinates using `m_map_gcmfaces.m`. This plot is generated by calling `‘example_display(4)’`.

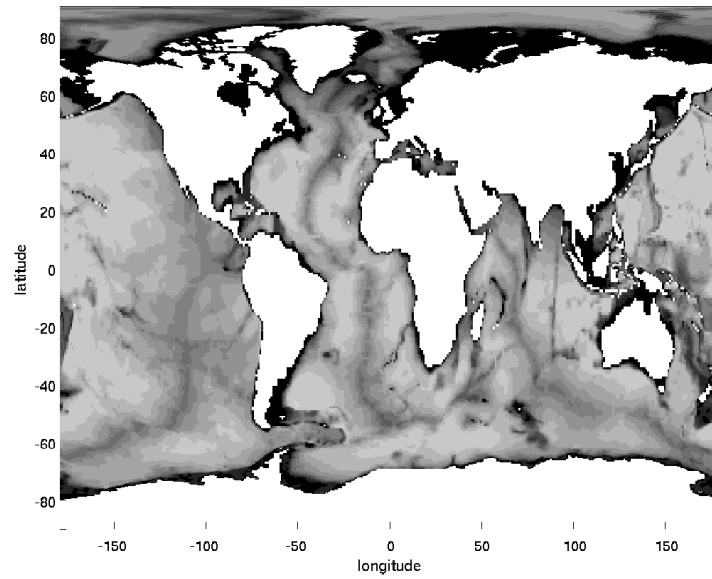


Figure 5: Same as Fig.3 but plotted in geographical coordinates using `convert2pcol.m`. This plot is generated by calling `'example_display(3)'`.

161 5 Standard Analysis

162 The gcmfaces ‘standard analysis’ consists of an extensive set of physical di-
163 agnostics that are routinely monitored in MITgcm simulations and ECCO v4
164 estimates. The computational loop is operated by `diags_driver.m` that ex-
165 pects the data organization shown in Fig.1. The results of `diags_driver.m`
166 get stored in a dedicated directory (`‘mat/’` in Fig.1). The display phase is
167 done afterwards by calling `diags_display.m` (simple display to screen)
168 or `diags_driver_tex.m` (to generate a tex file). The standard analysis of
169 ECCO v4 release 1 was published as the supplement to [Forget et al. \(2015\)](#).

170 Here it is assumed that the user has completed the installation proce-
171 dure in section 1.3 (including the installation of `‘nctiles_climatology/’` and
172 `‘m_map/’`). The code below then generates and displays mean and vari-
173 ance maps (`setDiags=‘B’` encoded in `diags_set_B.m`) from the ECCO v4
174 monthly mean climatology (12 monthly fields), which take ≈ 5 minutes:

```
175 %add paths:
176 p = genpath('gcmfaces/'); addpath(p);
177 p = genpath('MITprof/'); addpath(p);
178 p = genpath('m_map/'); addpath(p);
179
180 %compute diagnostics:
181 help diags_driver;
182 dirModel='release1/';
183 dirMat=[dirModel 'mat/'];
184 setDiags='B';
185 diags_driver(dirModel,dirMat,'climatology',setDiags);
186
187 %display results:
188 diags_display(dirMat,setDiags);
```

189 The generated plots have a caption that indicates the quantity being
 190 displayed. Other sets of diagnostic can be displayed similarly with different
 191 specifications of `setDiags`. Each one requires a specific set of model output.
 192 Sets of diagnostics that can be generated using ‘`nctiles_climatology/`’ include
 193 oceanic transports (‘A’), mean and variance maps (‘B’), sections and time
 194 series (‘C’), and mixed layer depths (‘MLD’).

195 If the ‘`setDiags`’ argument to `diags_driver.m` is omitted then the four
 196 diagnostic sets will be generated at once, which takes $\approx 1/2$ hour. Each set of
 197 diagnostics (computation and display) is encoded in one routine with a name
 198 such as ‘`diags_set_XX.m`’ (here ‘XX’ is just a placeholder). These routines
 199 can be found in the ‘`gcmfaces_diags/`’ directory and they are expected to be
 200 operated via `diags_driver.m`.

201 The plots generated by `diags_driver.m` can further be displayed via `di-`
 202 `ags_driver_tex.m` which will save them to disk and will create a compilable
 203 tex file including all of the plots. This can take an additional 10 minutes:

```
204 %compute more diagnostics:
205 dirModel='release1/'; dirMat=[dirModel 'mat/'];
206 diags_driver(dirModel,dirMat,'climatology');
207
208 %generate a tex file containing all of the plots:
209 dirTex=[dirModel 'tex/']; nameTex='standardAnalysis';
210 diags_driver_tex(dirMat,{},dirTex,nameTex);
```

211 These same diagnostics can be generated for the full ECCO v4 time se-
 212 ries: [ftp://mit.ecco-group.org/ecco_for_las/version_4/release1/nctiles/](http://mit.ecco-group.org/ecco_for_las/version_4/release1/nctiles/)
 213 The program expects ‘`nctiles/`’ to be placed next to ‘`nctiles_climatology/`’
 214 as depicted in Fig. 1. Since the 20 year time series consists of 240 monthly
 215 records, the computational times reported above are multiplied by 20. Thus

216

217 `diags_driver(dirModel,dirMat,[1992:2011]);`

218 is typically ran overnight. The computation can be distributed over multiple
219 processors by splitting [1992:2011] into several subsets.